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is an outdoor robot
designed to run
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unstructured
environments. It was
inspired by the
DARPA Grand
Challenge and built
as a prototype
vehicle for that

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**competition, in
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Rainwater of the
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Mike Hamilton, Mark
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implement steps.
They can be
implemented in
python (like Behave)
or just using other
Keywords , which
allows way more

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flexibility and
reusability of code.
It has a wider...
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The development
and growth of
industrial robots
started in 1947. The
velocity of this
process has
increased as a result

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of development
Human
technology. Now,
industrial robots
have broad
applications.

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pedestrian — it
drives on sidewalks.
And like

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pedestrians, it's
Human
pestered by road
crossings. Its idyllic,
carefree stroll is
promptly replaced
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