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ME C134 / EE C128: Feedback Control Systems (Spring 2018)  
thanks for all the books great work. 29 September 2015 (16:46) thankz

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Assume the system consists of mass  $M$ , where  $M$  is the mass of the dispensing system and the  $n$  plates, viscous friction,  $f_v$ , where the viscous friction originates where the piston meets the sides of the cylinder, and of course the spring with spring constant,  $K$ .

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