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we have a nonlinear multiobjective optimization problem. Problem is nondifferentiable if some functions are nondifferentiable and convex if all objectives and  $S$  are convex. Optimality | Contradiction and possible incommensurability ... Optimization, Kluwer (Springer), 1999. Methods cont.*

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*In this paper, based on the ordering relations induced by a pointed, closed and convex cone with a nonempty interior, we propose a nonlinear augmented Lagrangian dual scheme for a nonconvex multiobjective optimization problem by applying a class of vector-valued nonlinear augmented Lagrangian penalty functions. We establish the weak and strong duality results, necessary and sufficient ...*

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*LNCS 5252 - Introduction to Multiobjective Optimization ...*

*Numerous applications of multiobjective optimization available in various fields, e.g.\* ... Interactive and Evolutionary Approaches, Springer-Verlag, 2008. Solving MOPs in practice In practice, the following issues need to be ... includes continuous variables and nonlinear objectives and constraints needs to be considered from different ...*

*Nonlinear augmented Lagrangian for nonconvex ...*

*nonlinear programming, Kuhn and Tucker (1951) did also formulate them for multiobjective optimization problems. Typically, in the MCDM literature, the idea of solving a multiobjective optimization problem is understood as helping a human decision maker (DM) in considering the multiple objectives simultaneously and in finding a Pareto*

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*GA-based multi-objective optimization of active nonlinear quarter car suspension system—PID and fuzzy logic control Mahesh P. Nagarkar<sup>1,2\*</sup>, Yogesh J. Bhalerao<sup>3</sup>, Gahininath J. Vikhe Patil<sup>2</sup> and Rahul N. Zaware Patil<sup>4</sup> Abstract Background: The primary function of a suspension system is to isolate the vehicle body from road irregularities*

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*Introduction. A multi-objective optimization problem is an optimization problem that involves multiple objective functions. In mathematical terms, a multi-objective*

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*optimization problem can be formulated as  $((\rightarrow), (\rightarrow), \dots, (\rightarrow)) \rightarrow \mathbb{E}$ , where the integer  $\geq$  is the number of objectives and the set is the feasible set of decision vectors, which is typically  $\mathbb{E}$  but it depends of the ...*

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*Nonlinear Multiobjective Optimization, volume 12 of International Series in Operations Research and Management Science. Kluwer Academic Publishers, Dordrecht, The Netherlands, 1999. zbMATH Google Scholar*

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