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with the intuition behind Optimal Control Theory instead. We will make the following assumptions, 1. u is unconstrained, so that the solution will always be in the interior. In other

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Geared toward upper-level undergraduates, this text introduces three aspects of optimal control theory: dynamic programming, Pontryagin's minimum principle, and numerical techniques for trajectory optimization. Numerous problems, which introduce additional topics and

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1 Introduction to Optimal Control Theory

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